



(11) Publication number:

0

Generated Document.

## PATENT ABSTRACTS OF JAPAN

(21) Application number: 62165199

(51) Intl. Cl.: **G05B 13/00** G05B 15/02

(22) Application date: **03.07.87** 

(30) Priority:

publication:

(43) Date of application

13.01.89

(84) Designated contracting

states:

(71) Applicant: HITACHI LTD

(72) Inventor: SAKURAI YOSHIMI

SHIRAHAMA HIDEFUM

(74) Representative:

## (54) **DIGITAL CONTROLLER**

(57) Abstract:

PURPOSE: To realize the high-speed response and high accuracy of a digital controller by adding a variable limiter circuit and a variable gain circuit.

CONSTITUTION: An adder 2 calculates the deviation ε between the control input (u) and the internal state value (y) of a control system. A limiter circuit 3 functions to change its limiting range according to the value of the deviation εso that the rounding way of data is changed. A variable gain circuit 4 eliminates the variation of the loop gain caused by the rounding way of the deviation ε and ensures the fixed loop gain of a control system. In such a constitution, even the large deviation & epsi; does not affect the internal limit value of the control system and therefore the control value (y) can follow quickly the control input (u). Furthermore the highly accurate follow-up is possible in accordance with the deviation

ε even though this deviation is small.

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